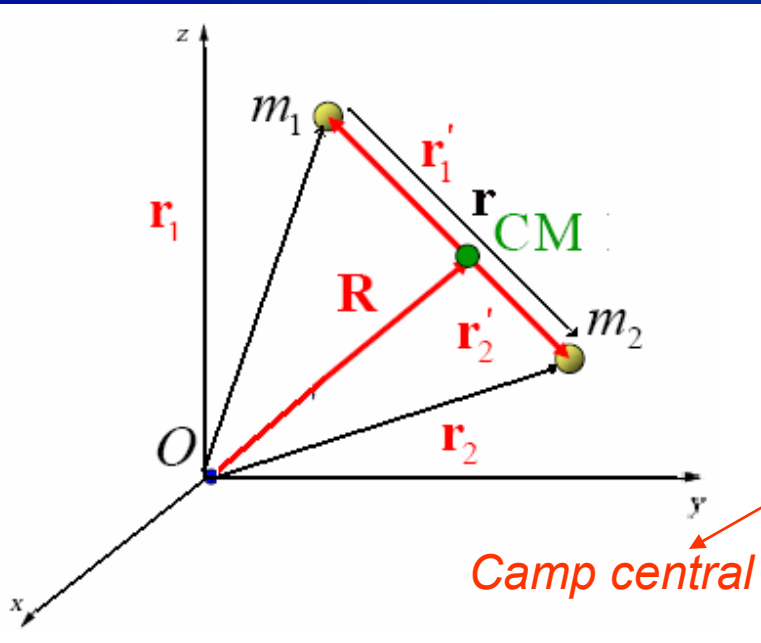


Miacarea in Camp Central de Forte

Problema celor doua corpuri



Ne propunem determinarea ecuatiilor de miscare pentru doua corpuri de mase m_1 si m_2 care interactioneaza unul cu altul prin intermediul unui camp central de forte.

$$F = f(r)\hat{r} = -\frac{\partial U}{\partial r}\hat{r}; \quad \hat{r} = \frac{\mathbf{r}}{r} = \frac{\mathbf{r}_1 - \mathbf{r}_2}{|\mathbf{r}_1 - \mathbf{r}_2|}; \quad r = |\mathbf{r}_1 - \mathbf{r}_2|$$

Informatii mai bune putem obtine exprimand pozitia centrului de masa (CM)

$$\mathbf{R} = \frac{m_1\mathbf{r}_1 + m_2\mathbf{r}_2}{m_1 + m_2}$$

Dorim deci , exprimarea vectorilor \mathbf{r}_1 si \mathbf{r}_2 ca functii de r si \mathbf{R}

$$\left. \begin{aligned} r &= \mathbf{r}_1 - \mathbf{r}_2 \\ \frac{(m_1 + m_2)\mathbf{R}}{m_2} &= \frac{m_1}{m_2}\mathbf{r}_1 + \mathbf{r}_2 \end{aligned} \right\} (+)$$



$$\mathbf{r}_1 = \frac{m_2}{m_1 + m_2} \left(r + \frac{(m_1 + m_2)\mathbf{R}}{m_2} \right)$$



$$r_1 = R + \frac{m_2}{m_1 + m_2} r$$

$$r_2 = R - \frac{m_1}{m_1 + m_2} r$$

Functia Lagrange pentru sistem devine:

$$L = \frac{1}{2} m_1 \dot{r}_1^2 + \frac{1}{2} m_2 \dot{r}_2^2 - U(r) =$$

$$= \frac{m_1}{2} \left(\dot{R} + \frac{m_2}{M} \dot{r} \right)^2 + \frac{m_2}{2} \left(\dot{R} - \frac{m_1}{M} \dot{r} \right)^2 - U(r); \quad M = m_1 + m_2$$

notand

$$\mu = \frac{m_1 m_2}{m_1 + m_2} \text{ masa redusa a sistemului}$$

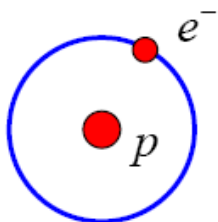
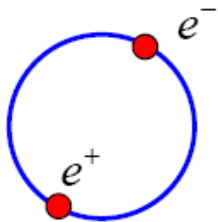


$$L = \frac{1}{2} M \dot{R}^2 + \frac{1}{2} \mu \dot{r}^2 - U(r)$$

$$\mu_{\text{positronium}} = \frac{m_e m_e}{(m_e + m_e)} = \frac{m_e}{2}$$

$$m(p) \gg m(e^+)$$

$$\mu_{\text{hydrogen}} = \frac{m_p m_e}{(m_p + m_e)} \approx m_e$$



$$V(r) = -\frac{q^2}{r}$$

Aceleasi rezultatele obtinem alegand CM ca noua origine a sistemului

$$\dot{r}_1 = r_1 - R$$

$$\dot{r}_2 = r_2 - R$$

Teorema lui König

$$m_1 \dot{r}_1 + m_2 \dot{r}_2 = 0$$

notand

$$M = m_1 + m_2$$

$$r = r_1 - r_2 = \dot{r}_1 - \dot{r}_2$$

$$\dot{r}_1 = \frac{m_2}{M} r$$

$$\dot{r}_2 = -\frac{m_1}{M} r$$

$$L = \frac{1}{2} M V_{\text{CM}}^2 + \frac{1}{2} \mu \dot{r}^2 - U(r)$$

$$L = \frac{1}{2} M \dot{R}^2 + \frac{1}{2} \mu \dot{r}^2 - U(r)$$

a)

$$\frac{\partial L}{\partial \dot{R}} = M \dot{R}$$
$$\frac{\partial L}{\partial R} = 0$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{R}} \right) - \frac{\partial L}{\partial R} = 0$$

$$\Rightarrow M \ddot{R} = 0 \Rightarrow$$

$$M \dot{R} = \text{const.}$$

$$\begin{cases} M\mathbf{R} = M \left(\frac{m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2}{m_1 + m_2} \right) = m_1 \mathbf{r}_1 + m_2 \mathbf{r}_2 = \mathbf{p}_1 + \mathbf{p}_2 \\ M\mathbf{R} = \mathbf{p}_{\text{Total}} \end{cases}$$

$$\Rightarrow \mathbf{p}_{\text{Total}} = \mathbf{p}_1 + \mathbf{p}_2$$

Impulsul total se conserva

b)

$$\frac{\partial L}{\partial \mathbf{r}} = \mu \hat{\mathbf{r}}$$

$$\frac{\partial L}{\partial \mathbf{r}} = -\frac{\partial U}{\partial r} \frac{\mathbf{r}}{r} = -\frac{\partial U}{\partial r} \hat{\mathbf{r}}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\mathbf{r}}} \right) - \frac{\partial L}{\partial \mathbf{r}} = 0$$

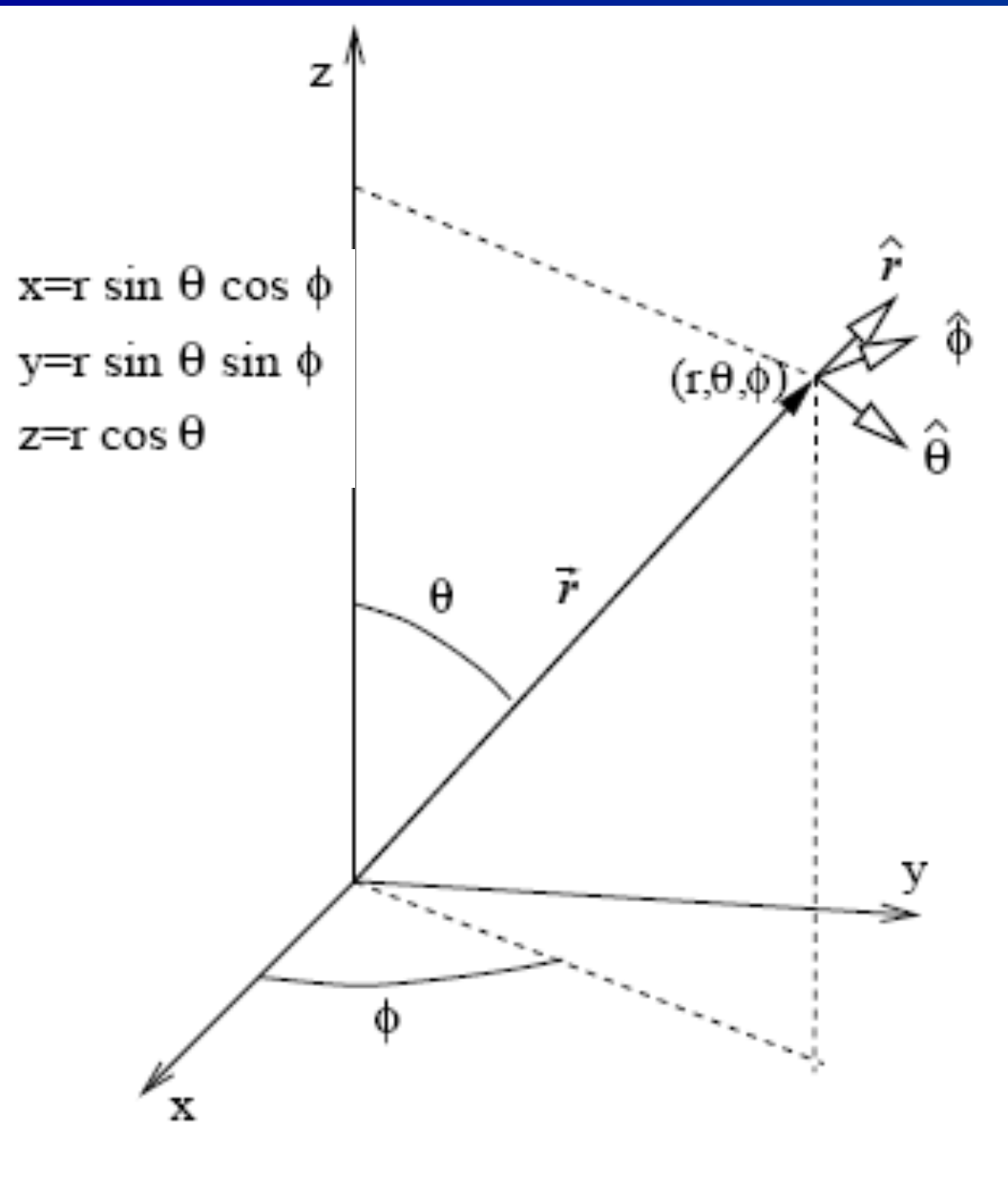
$$\Rightarrow \mu \hat{\mathbf{r}} + \frac{\partial U}{\partial r} \hat{\mathbf{r}} = 0$$

\Rightarrow *Miscarea a doua puncte materiale care interactioneaza intre ele, se reduce la problema miscarii unui punct de masa μ intr-un camp exterior*

Observam ca a) si b) nu sunt cuplate si deci miscarea CM $R(t)$ este decuplata de miscarea relativa $r(t)$

\Rightarrow *Putem ignora miscarea CM ($R(t)$)*

Sistemul campului central de forta are simetrie sferica



→ Se poate roti in jurul oricarei axe ce trece prin origine



Simetrie rotatională

• Lagrangianul nu depinde de direcție

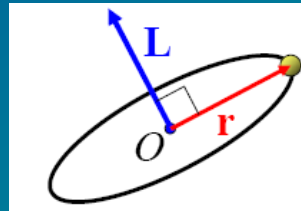
$$L = T(\dot{\vec{r}}) - U(r)$$

→ Momentul unghiular se conserva

$$\vec{L} = \vec{r} \times \vec{p} = \text{const.}$$

$$\vec{L} \cdot \vec{r} = (\vec{r} \times \vec{p}) \cdot \vec{r} = 0$$

$$\vec{r} \perp \vec{L}$$



→ Traectoria $r(t)$ este continuată in întregime într-un plan ortogonal cu L

→ Putem parametriza traectoria $r(t)$ în termenii coord. polare

$$\mathbf{r} = r \hat{e}_r + r\phi \hat{e}_\theta$$

Lagrangianul in coordonate polare va fi:

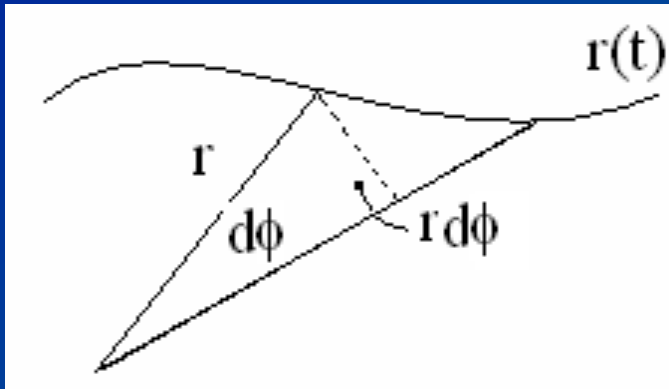
$$L = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) - U(r)$$

Observam ca ϕ este coordonata ciclica, momentul sau conjugat p_ϕ se conserva

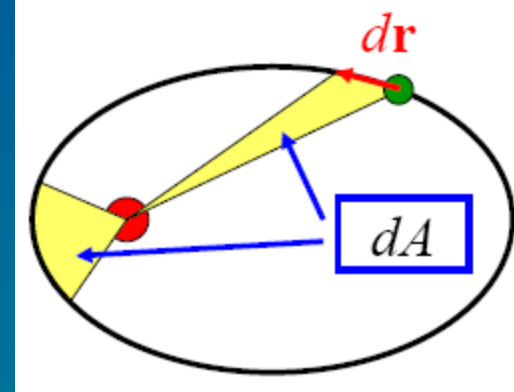
$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = \mu r^2 \dot{\phi} \equiv l$$

Marimea momentului unghiular

Introducem notiunea de "viteza areolara"



Legea a II a a lui Kepler:
Vectorul de pozitie al unei planete matura arii egale in intervale de timp egale



$$dA = \frac{1}{2} r(r d\phi) = \frac{1}{2} r^2 d\phi$$

$$\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\phi} = \frac{1}{2} \frac{l}{\mu} = \text{const.}$$

viteza areolara

Miscarea planetei este mai rapida cand orbita este mai apropiata de origine

Stabilim ecuatia Lagrange

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) - \frac{\partial L}{\partial r} = 0 \Rightarrow \mu \ddot{r} - \mu r \dot{\phi}^2 + \frac{\partial U}{\partial r} = 0$$

Fora centrifuga

Fora centrala

$$\dot{\phi} = \frac{l}{\mu r^2}$$

$$\mu \ddot{r} - \frac{l^2}{\mu r^3} + \frac{\partial U}{\partial r} = 0$$

insa

$$\ddot{r} = \frac{dr}{dt} = \frac{dr}{dr} \frac{dr}{dt} = \frac{dr}{dr} \dot{r} \quad \mu \frac{dr}{dr} \dot{r} = \frac{l^2}{\mu r^3} - \frac{\partial U}{\partial r}$$

$$\int \mu \dot{r} dr = \int \left(\frac{l^2}{\mu r^3} - \frac{\partial U}{\partial r} \right) dr \Rightarrow \frac{1}{2} \mu \dot{r}^2 = -\frac{1}{2} \frac{l^2}{\mu r^2} - U(r) + E$$

$$E = \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \frac{l^2}{\mu r^2} + U(r)$$

E = constanta de integrare

$$U_{ef}(r) = \frac{l^2}{2\mu r^2} + U(r)$$

Conservarea energiei

$$E = T + U(r) = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) + U(r)$$

Din ecuatia Lagrange

$$\mu \ddot{r} - \frac{l^2}{\mu r^3} + \frac{\partial U}{\partial r} = 0 \quad \Rightarrow \quad \mu \ddot{r} = -\frac{d}{dr} \left[U(r) + \frac{1}{2} \frac{l^2}{\mu r^2} \right]$$

Inmultind cu r

$$\Rightarrow \mu r \ddot{r} = -r \frac{d}{dr} \left[U(r) + \frac{1}{2} \frac{l^2}{\mu r^2} \right]$$

deoarece

$$\mu r \ddot{r} = \frac{d}{dt} \left(\frac{1}{2} \mu \dot{r}^2 \right)$$

$$-r \frac{d}{dr} = -\frac{dr}{dt} \frac{d}{dr} = -\frac{d}{dt}$$

$$\Rightarrow \frac{d}{dt} \left[\frac{1}{2} \mu \dot{r}^2 + U(r) + \frac{1}{2} \frac{l^2}{\mu r^2} \right] = 0 \quad \text{Astfel} \quad \frac{1}{2} \mu \dot{r}^2 + U(r) + \frac{1}{2} \frac{l^2}{\mu r^2} = \text{const.}$$

deoarece

$$\frac{l^2}{2\mu r^2} = \frac{\mu r^2 \dot{\phi}^2}{2} \quad \Rightarrow$$

$$E = T + U(r) = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\phi}^2) + U(r) = \text{const.}$$

Ecuatia Lagrange devine:

$$\mu \ddot{r} = - \frac{\partial U_{ef}(r)}{\partial r}$$

Miscarea unei particule intr-un potential efectiv

Energia:

$$E = \frac{1}{2} \mu \dot{r}^2 + U_{ef}(r)$$

$$\dot{r} = \frac{dr}{dt} = \pm \sqrt{\frac{2}{\mu} (E - U_{ef}(r))}$$

$$t = \pm \int_{r_0}^r \frac{dr}{\sqrt{\frac{2}{\mu} (E - U_{ef}(r))}} + const \equiv r(t)$$

$$\dot{\varphi} = \frac{l}{\mu r^2} = \frac{d\varphi}{dt}$$

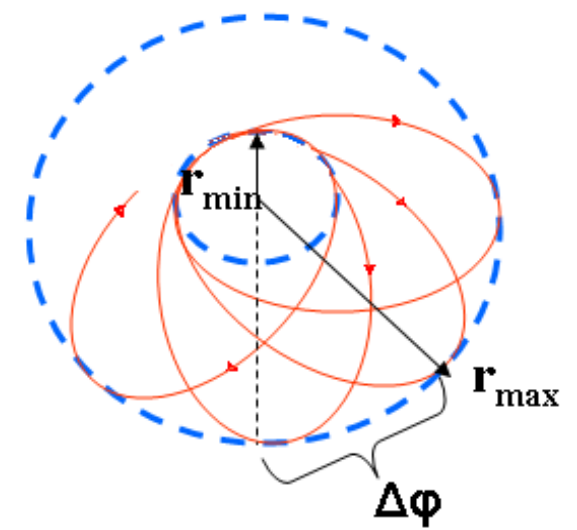
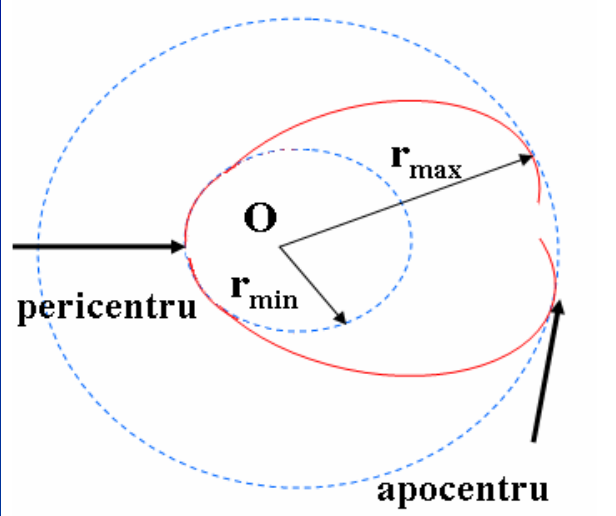
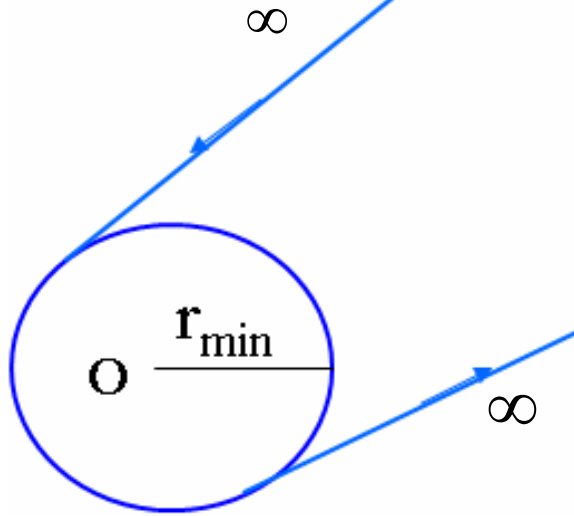
$$\varphi(t) = \int_0^t \frac{l}{\mu [r(t)]^2} dt + \varphi_0$$

Pentru valori date ale E si l (marimi care se conserva) cautam r(phi) :

$$\dot{r} = \frac{dr}{d\varphi} \dot{\varphi} = \frac{dr}{d\varphi} \frac{l}{\mu r^2} = \pm \sqrt{\frac{2}{\mu} (E - U_{ef})}$$

$$\varphi = \pm \int_{r_0}^r \frac{l}{r^2 \sqrt{2\mu(E - U_{ef})}} dr + const \equiv \varphi(r)$$

Ecuatia traiectoriei



r_0 are semnificatie fizica daca $E \geq U_{ef}(r)$

- valorile lui r pentru care $E = U_{ef}(r)$ definesc limitele intervalului de valori permise in timpul miscarii
- punctul in care $r_0 = 0$ =punct de intoarcere
- daca r_{min} este o radacina pozitiva a ec. $E = U_{ef}(r)$ si sunt permise pentru r toate radacinile cuprinse intre (r_{min}, ∞) si daca $r_0 > r_{min}$ misc. particulei este nelimitata

- daca ecuatia $E = U_{ef}(r)$ are radacini distincte si pozitive, $r_{min} < r_{max}$ si daca in intervalul $r \in [r_{min}, r_{max}]$ este verificata inegalitatea $E \geq U_{ef}(r)$ atunci miscarea este limitata
- Intreaga traiectorie este continuta intr-o coroana circulara

$$\Delta\phi = \pm \int_{r_{min}}^{r_{max}} \frac{l}{r^2 \sqrt{2\mu(E - U_{ef})}} dr$$

$$n \cdot \Delta\phi = m \cdot 2\pi; \quad (n, m \geq 1)$$

$$\Delta\phi = \frac{m}{n} \cdot 2\pi$$

Conditia de "inchidere" a traiectoriei (raza vectoare a punctului, dupa ce a efectuat m rotatii complete, isi va regasi valoarea initiala)

$$U(r) = \begin{cases} -\frac{k}{r} \\ kr^2 \end{cases}$$

Ecuatia diferentiala a orbitei

Am gasit forma generala pentru $r=r(\varphi)$ sau $r=r(t)$ si cateva constante E, l etc. si cautam $r=r(\varphi)$ eliminand parametrul timp, ceea ce inseamna ecuatia orbitei.

$$\mu r^2 \dot{\varphi} = l$$

$$\Rightarrow \mu r^2 \frac{d\varphi}{dt} = l \Rightarrow \mu r^2 d\varphi = l dt$$

$$\Rightarrow \frac{d}{dt} = \frac{l}{\mu r^2} \frac{d}{d\varphi}$$

$$\frac{d^2}{dt^2} = \frac{l}{\mu r^2} \frac{d}{d\varphi} \left(\frac{l}{\mu r^2} \frac{d}{d\varphi} \right) \text{ Inlocuind in}$$

ecuatia Lagrange

$$\mu \ddot{r} - \frac{l^2}{\mu r^3} = -\frac{\partial U}{\partial r} = f(r)$$

$$\frac{1}{r^2} \frac{d}{d\varphi} \left(\frac{l}{\mu r^2} \frac{dr}{d\varphi} \right) - \frac{l^2}{\mu r^3} = f(r)$$

Insa $\frac{1}{r^2} \frac{dr}{d\varphi} = -\frac{d}{d\varphi} \left(\frac{1}{r} \right)$ *si introducand* $u = \frac{1}{r}$ *rezulta*

$$\frac{l^2 u^2}{\mu} \left(\frac{d^2 u}{d\varphi^2} + u \right) = -f \left(\frac{1}{u} \right)$$

deoarece

$$\frac{d}{du} = \frac{dr}{d\varphi} \frac{d}{dr} = -\frac{1}{u^2} \frac{d}{dr}$$

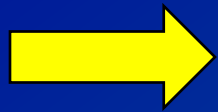
rezulta

$$\frac{d^2 u}{d\varphi^2} + u = -\frac{\mu}{l^2} \frac{d}{du} U \left(\frac{1}{u} \right)$$

Ec.diferentiala a orbitei (ecuatia Binet) daca se cunosc f sau U

*Pentru un
potential oarecare*

$$d\varphi = \frac{l dr}{\mu r^2 \sqrt{\frac{2}{\mu} (E - U_{ef}(r))}} = \frac{l dr}{\mu r^2 \sqrt{\frac{2}{\mu} \left(E - U(r) - \frac{l^2}{2\mu r^2} \right)}}$$



$$\varphi = \int_{r_0}^r \frac{dr}{r^2 \sqrt{\frac{2\mu E}{l^2} - \frac{2\mu U}{l^2} - \frac{1}{r^2}}} + \varphi_0$$

*Ecuatie ce da φ ca functie
de r si constantele E, l, r_0*

Facand schimbarea de variabila

$$u = \frac{1}{r}$$



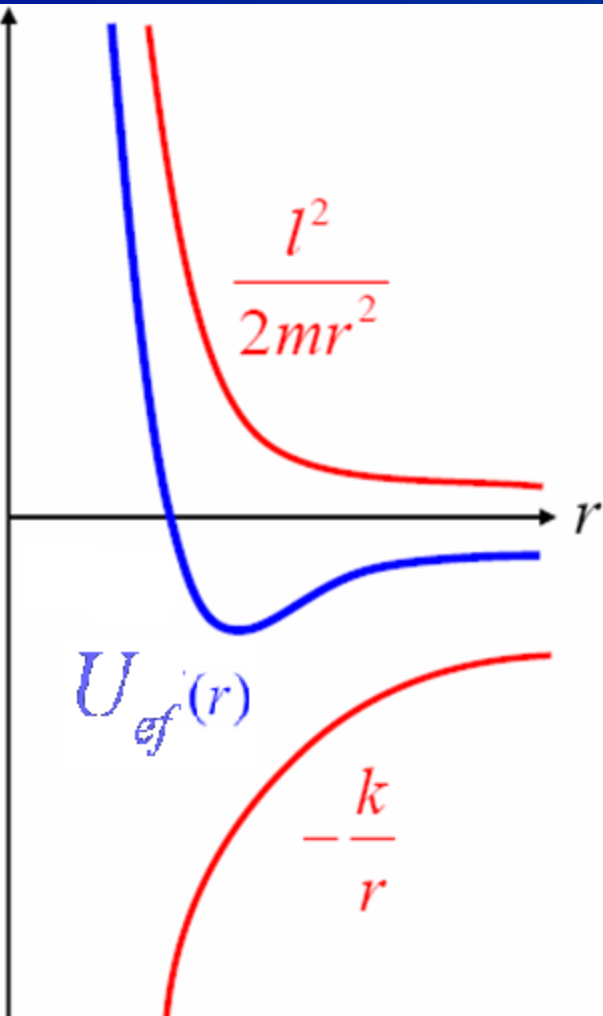
$$\varphi = \varphi_0 - \int_{u_0}^u \frac{du}{\sqrt{\frac{2\mu E}{l^2} - \frac{2\mu U}{l^2} - u^2}}$$

Ecuatia formala a orbitei

Problema lui Kepler

$$f(r) = -\frac{k}{r^2} \Rightarrow U(r) = -\frac{k}{r}$$

$$U_{ef} = -\frac{k}{r} + \frac{l^2}{2mr^2}$$



$$\frac{d^2u}{d\varphi^2} + u = -\frac{m}{l^2 u^2} f\left(\frac{1}{u}\right)$$

$$\frac{d^2u}{d\varphi^2} + u = -\frac{m}{l^2} \frac{d}{du} U\left(\frac{1}{u}\right)$$



$$\frac{d^2u}{d\varphi^2} + u = \frac{mk}{l^2}$$

Facem schimbarea de variabila $y = u - \frac{mk}{l^2}$

$$\frac{d^2y}{d\varphi^2} + y = 0$$



$$y = C \cos(\varphi - \varphi')$$

$C, \varphi' = \text{const. de integrare}$



notam $\varepsilon = C \frac{l^2}{mk}$

$$\frac{1}{r} = \frac{mk}{l^2} [1 + \varepsilon \cos(\varphi - \varphi')]$$

$$\varphi = \varphi_0 - \int \frac{du}{\sqrt{\frac{2mE}{l^2} - \frac{2mU}{l^2} - u^2}}$$

insa $\int \frac{dx}{\sqrt{a+bx+cx^2}} = \frac{1}{\sqrt{-c}} \arccos \left[-\frac{b+2cx}{\sqrt{b^2-4ac}} \right] \quad a = \frac{2mE}{l^2}; \quad b = \frac{2mk}{l^2}; \quad c = -1$

$$\int d\varphi = - \int \frac{du}{\sqrt{\frac{2mE}{l^2} + \frac{2mku}{l^2} - u^2}} = - \int \frac{du}{\sqrt{\frac{2mE}{l^2} + \frac{m^2k^2}{l^4} - \left(\frac{mk}{l^2} - u\right)^2}} =$$

$$= - \frac{1}{\sqrt{\frac{2mE}{l^2} + \frac{m^2k^2}{l^4}}} \int \frac{du}{\sqrt{1 - \left(\frac{\frac{mk}{l^2} - u}{\sqrt{\frac{2mE}{l^2} + \frac{m^2k^2}{l^4}}} \right)^2}} \quad du = \sqrt{\frac{2mE}{l^2} + \frac{m^2k^2}{l^4}} \sin \omega d\omega$$

\uparrow
COS ω

$$= -\int \frac{\sin \omega}{\sin \omega} d\omega = -\omega \quad \longrightarrow \quad \cos \omega = \cos(\varphi - \varphi') = \frac{\frac{mk}{l^2} - u}{\sqrt{\frac{2mE}{l^2} + \frac{m^2 k^2}{l^4}}}$$

$$\varphi = \varphi' - \arccos \left[\frac{\frac{l^2 u}{mk} - 1}{\sqrt{1 + \frac{2El^2}{mk^2}}} \right]$$

deoarece $u = \frac{1}{r}$

$$u = \frac{1}{r} = \frac{mk}{l^2} \left[1 + \sqrt{1 + \frac{2El^2}{mk^2}} \cos(\varphi - \varphi') \right] = \frac{mk}{l^2} [1 + \varepsilon \cos(\varphi - \varphi')]$$

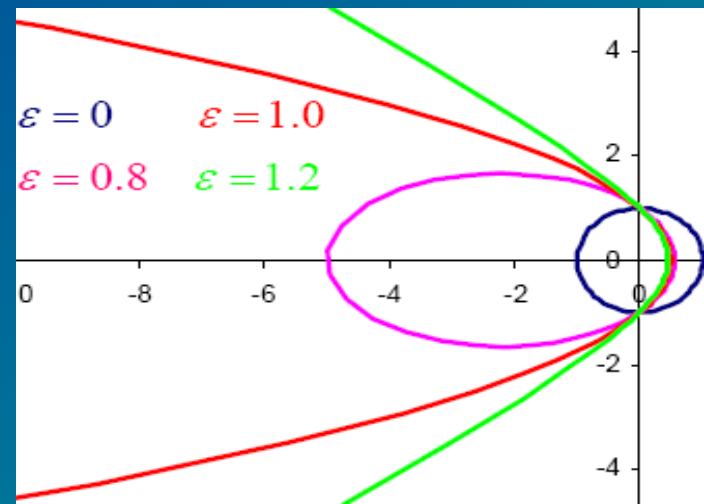
Ecuatia generala a conice (ε fiind excentricitatea)

$\varepsilon > 1, \quad E > 0$: hiperbola

$\varepsilon = 1, \quad E = 0$: parabola

$\varepsilon < 1, \quad E < 0$: elipsa

$\varepsilon = 0, \quad E = -\frac{mk^2}{2l^2}$: cerc



Orbite nemarginite

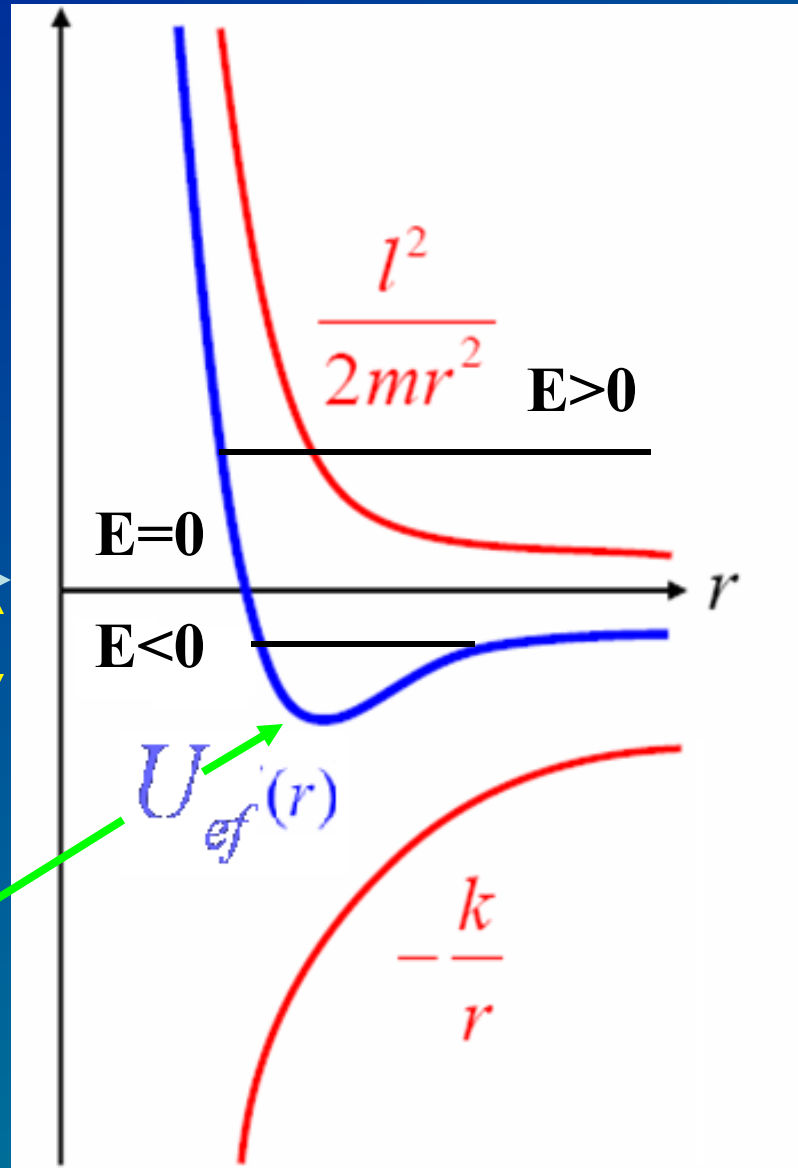
Hiperbola

Parabola

Orbite marginite

Elipsa

Cerc



$$U_{ef}(r_0) = -\frac{k}{r_0} + \frac{l^2}{2mr_0^2} = E$$

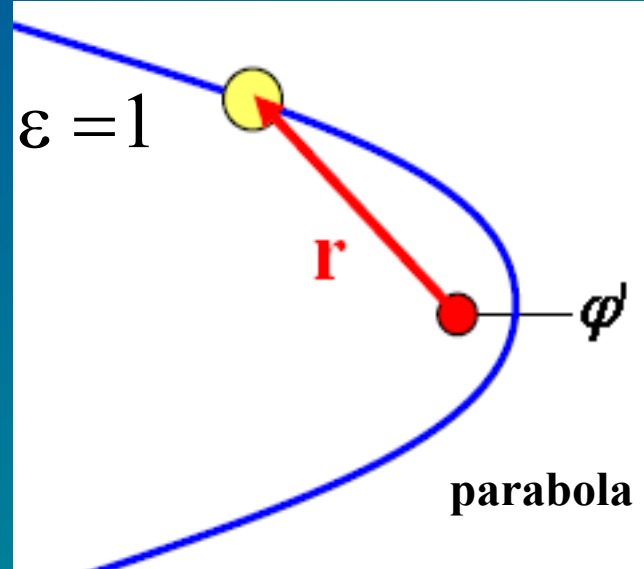
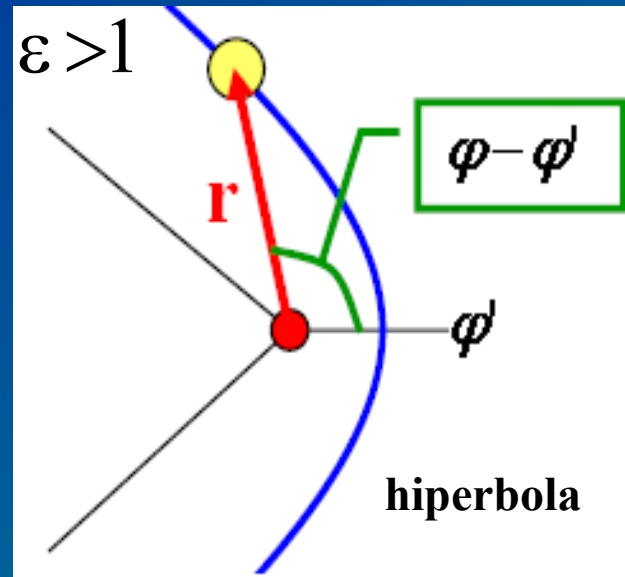
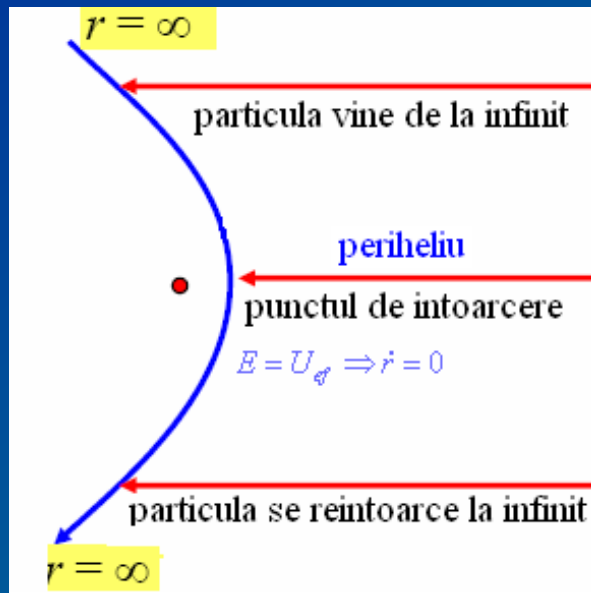
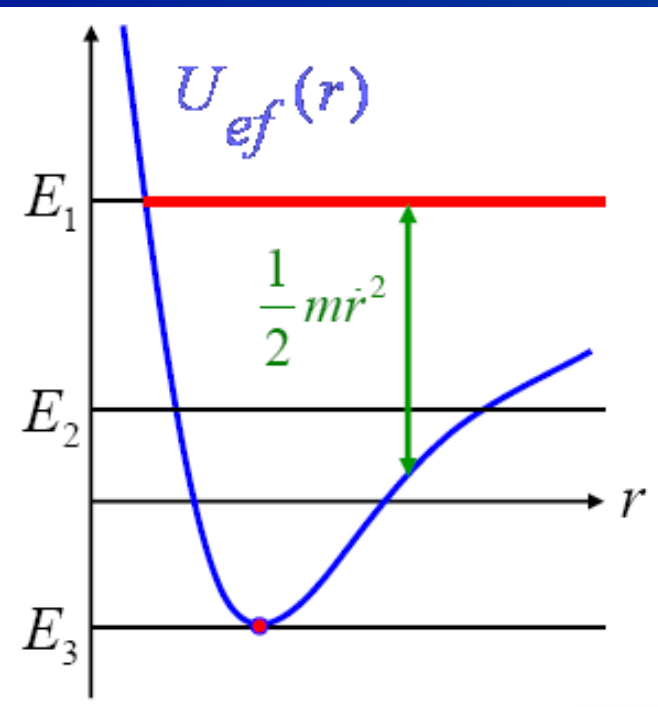
$$\left. \frac{dU_{ef}}{dr} \right|_{r_0} = \frac{k}{r_0^2} - \frac{l^2}{mr_0^3} = 0$$

$$E = -\frac{mk^2}{2l^2}$$

Orbite nemarginite

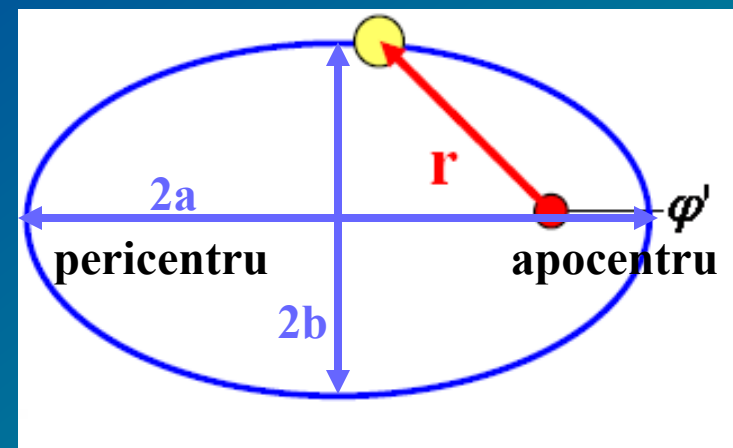
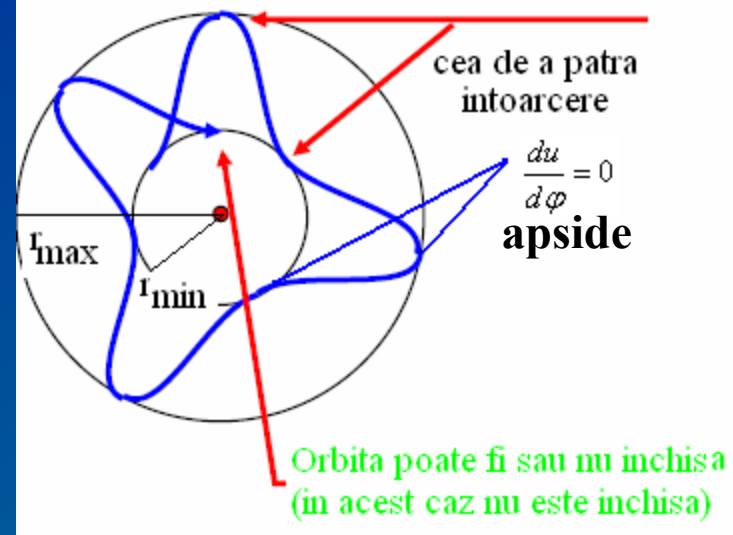
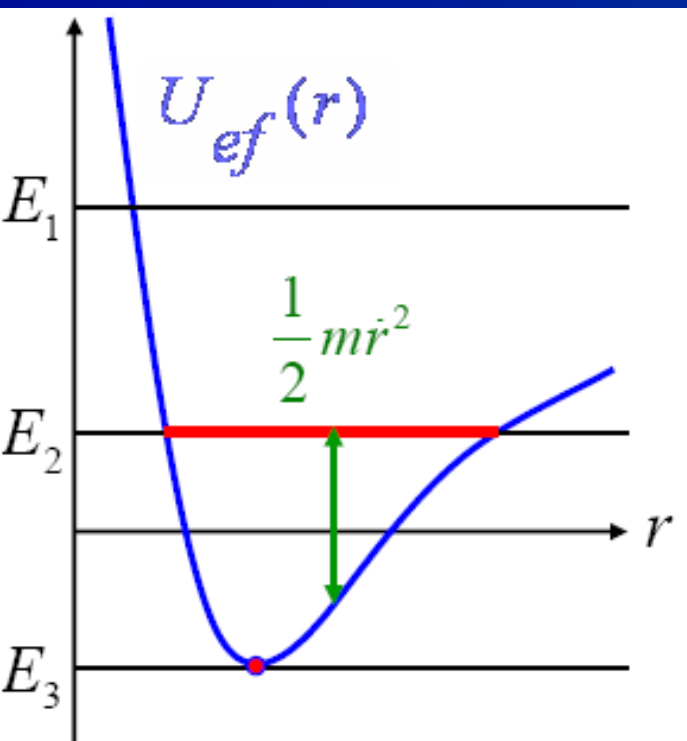
$$E = E_1 \Rightarrow r < r_{\min} \quad E_1 = U_{ef}(r_{\min})$$

$$\cos(\varphi - \varphi') > -\frac{1}{\varepsilon} \quad \text{limiteaza valoarea lui } \theta$$



Orbite marginite

$$E = E_2 \Rightarrow r_{\min} < r < r_{\max}$$



$$\frac{1}{r} = \frac{mk}{l^2} (1 \pm \varepsilon)$$

Lungimea axei mari

$$a = \frac{l^2}{2mk} \left(\frac{1}{1+\varepsilon} + \frac{1}{1-\varepsilon} \right) = -\frac{k}{2E}$$

Lungimea axei mici

$$b = a\sqrt{1-\varepsilon^2} = \sqrt{-\frac{l^2}{2mE}}$$

Aria orbitei

$$A = \pi ab = \pi \sqrt{-\frac{l^2 k^2}{8mE^3}}$$

Viteza areolara

$$\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\phi} = \frac{l}{m}$$

Perioada de rotatie

$$T_{rot} = \frac{A}{\left(\frac{dA}{dt}\right)} = \pi \sqrt{-\frac{mk^2}{2E^3}} = 2\pi \sqrt{\frac{m}{k} a^3}$$

Legea a treia a lui Kepler

daca

$$f = -\frac{k}{r^2} = -G \frac{Mm}{r^2}$$

$$T_{rot} = 2\pi \sqrt{\frac{\mu}{k} a^3} = \beta a^{\frac{3}{2}}; \quad \beta = 2\pi \sqrt{\frac{1}{G(m+M)}}$$

este acelasi pentru toate planetele daca $M \gg m$

